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Signals and Systems using MATLAB by Luis Chaparro, 9780128142042, available at Book Depository with free delivery worldwide. chaparro matlab solutions - Bing - shutupbill.com The Z-transform is used to obtain system realizations and the solution of the system. MATLAB is used to find the direct and inverse Z-transforms.

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Chaparro-Akan — Signals and Systems using MATLAB 0.3 0.2 Use Euler's identity to (a) show that (i) $\cos^2 = \sin^2$; (ii) $\sin^2 = \cos^2$; (iii) $\cos^2 = \sin^2 + \cos^2$; (b) to find (i) $\int_0^1 \cos^2 t dt$; (ii) $\int_0^1 \cos^2 t dt$; Answers: (b) 0 and 1=2. Solution (a) We have $i \cos^2 = 0.5(e^{j2t} + e^{-j2t}) = j0.5(e^{j2t} - e^{-j2t}) = \sin(2t)$ ii.

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Chaparro-Akan — Signals and Systems using MATLAB 0.7 0.6 Differential and difference equations — Find the ordinary differential equation relating a current source $i(t) = \cos(\omega t)$ with the current $i_L(t)$ in an inductor, with inductance $L = 1$ Henry, connected in parallel with a resistor of $R = 1$ (see Fig. 3).

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Chaparro Signals and Systems using MATLAB 1.9 Pr. 1.6 (a) The exponentials are defined from $t = 0$ so is a decaying exponential, while e^t is an increasing exponential. Their sum gives an even and positive function, the hyperbolic cosine, while their difference gives an odd function hyperbolic sine.

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